Query processing part 2 Algorithms

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Prerequired knowledge:

- indexing techniques (lecture)
- external sorting (lecture)
- Query processing part 1: algebraic optimization (lecture)

Global view

- We will not go into detail with respect to step 1
- The lecture on algebraic optimization deals with step 2
- We will now focus on step 3

- Disk IO is block (page) based; typical block size is 8 256 kB
- For our analysis, we suppose that tables are stored in an unordered collections of blocks
- Random access time can be minimized by indexing techniques
- Average access time can be enhanced by clustering

- To analyze performance of database access methods, we ignore internal memory access and only count IO (i.e. the number of disk accesses)
- ... although nowadays, analytical databases often are based on main memory storage techniques

$$
S:=\sigma_p(R)
$$

$$
p: A_1 = c_1 \wedge A_2 = c_2 \wedge \ldots \wedge A_n = c_n
$$

- Option 1: scan table R and apply predicate p to each tuple
- Option 2: if possible, use an index on one of the attributes A_i in p ; check the retrieved tuples for the other selection requirements
- But what if R has more indices connected to $attr(p)$?
- Using more than one index and calculating intersections is an option, but more efficient solutions are available

$$
S:=\sigma_p(R)
$$

- Option 2: if possible, use an index on one of the attributes in p
- But what if R has more than one index connected to $attr(p)$?
- Selections on some attributes can be more selective than others
- Compare attributes *birthdate* (including year) and *weight* in kg for people
- The larger the number of values for an attribute, the higher the selectivity of the selection for that attribute

How to deal with statistics of the results of an algebraic operator?

- For each table R, we keep track of the number of tuples $T(R)$
- For each table R , we keep track of the number of blocks $B(R)$ on disk that R resides in
- In most cases, we know the tuple size in bytes, so we can estimate $B(R)$ from $T(R)$
- In general, a disk block will contain several tuples
- \bullet For each table R and each attribute A in attr(R), we keep track of $V(R, A)$, i.e. the number of different values in $\pi_A(R)$

Table statistics: example

- \bullet $T(Bike) = 5$
- $B(Bike) = ?$, depends on ratio block size vs tuple size
- $V(Bike, type) = 2$; $V(Bike, frame) = 2$; $V(Bike, gear) = 3$
- $V(Bike, bike_id) = 5$; equals $T(Bike)$, because bike id is primary key

$$
S:=\sigma_p(R)
$$

- Option 2: if possible, use an index on one of the attributes in p
- \bullet But what if R has two indexed attributes: A and B?
- Choose the index on A if $V(R, A) \ge V(R, B)$, else otherwise

$$
S:=\sigma_{A=c}(R)
$$

- \bullet $T(S) \approx T(R)/V(R,A)$
- \bullet B(S) can be estimated from $T(S)$, given the ratio block size vs tuple size
- $V(S, A) = 1$
- Estimating $V(S, B)$ for other attributes B in $attr(S)$ is more tricky, but often unneccessary

Table statistics: histograms

$$
S:=\sigma_{A=c}(R)
$$

- Compare $city = 'Amsterdam'$ with $city = 'Giethoorn'$
- The distribution of $V(R, A)$ may be very uneven
- \bullet Refinement: histograms of value frequencies
- **•** Example: attribute weight in kg for table Patient in a hospital

- Possible problem: size of statistics database
- Technique: interval histograms

- Expected number of hits for *weight* $= 72$ equals 4.75
- Expected number of hits for *weight* $= 77$ equals 2.75

- Problem: maintenance of statistics database
- Observation: statistics do not need to be 100% correct
- Option: less frequent (partial) updating
- In case of extreme large databases, analyzing a small snapshot of the database in advance, to obtain statistics, is a possible technique

$$
U:=R\bowtie S
$$

- Suppose we have one join attribute: A
- We will denote this situation by $U := R \bowtie_A S$
- Available statistics: $T(R)$, $T(S)$, $V(R, A)$, $V(S, A)$
- Can we estimate $T(U)$?
- A good estimation for $T(U)$ is required when choosing between different join methods
- A good estimation for $T(U)$ is required when determining a join order for a join chain $R_1 \bowtie R_2 \bowtie \ldots \bowtie R_n$

Join estimations

- \bullet Let us fix our attention on a specific tuple t in R having A-value 327
- The estimated number of matching tuples for T in S equals $T(S)/V(S, A)$
- This results in $T(U) = T(R)T(S)/V(S, A)$

Join estimations

- Let us apply a modest feeling of symmetry
- \bullet The estimated number of matching tuples in R equals $T(R)/V(R,A)$
- This results in $T(U) = T(S)T(R)/V(R, A)$

$$
U:=R\bowtie_A S
$$

• We have two estimations for $T(U)$

$$
\bullet \ \mathcal{T}(U) = \mathcal{T}(R)\mathcal{T}(S)/\mathcal{V}(S,A)
$$

- \bullet $T(U) = T(R)T(S)/V(R, A)$
- We choose the minimum value of these two estimations
- Rationale: joins are in most cases asymmetric
- Special case: $R[A]$ is primary key and $S[A]$ is foreign key
- Then: $\pi_A S \subseteq \pi_A R$, $V(R, A) = T(R)$ and $T(U) = T(S)$

$$
U:=R\bowtie_A S
$$

- When analyzing performance, we will estimate the number of disk accessess (IO)
- Recall that an estimation of $T(R)$ also gives you an estimation of $B(R)$
- We have the horrible feeling that the number of IO's is proportional to $T(R)T(S)$...
- \bullet ... or at least to $B(R)B(S)$
- But we will see that $O(B(R) + B(S))$ is feasible!
- When comparing algorithms, we will ignore the IO of writing the final result table

$$
U:=R\bowtie_A S
$$

- General assumption: we have a main memory buffer size of M blocks to process joins
- ... although we silently suppose there is some extra buffer space for collecting output data
- We will discuss four join algorithms
- **1** Block nested loop
- **2** Index nested loop
- **3** Sort-Merge join
- ⁴ Hash join

Join algorithms: Block nested loop

}

- Suppose S has the smallest number of blocks
- Split S in chunks, each of size $M 1$ blocks (at most)

```
foreach chunk Ci of M-1 blocks of S {
  read Ci into main memory;
  foreach block B of R {
    read B into the free memory buffer;
    check all possible combinations
    of tuples t1 in chunk Ci and t2 in B2;
    if (t1.A = t2.A)write the join of these tuples to output;
  }
```
Join algorithms: Block nested loop

- Each chunk C_i of S is read once; total IO for S is $B(S)$
- The number of times the outer loop runs: $[B(S)/(M-1)]$
- For each run of the outer loop, we need $B(R)$ disk accesses to scan R
- Total IO for both tables: $B(S) + [B(S)/(M-1)] * B(R)$
- Now suppose $B(S) < M$, then $IO = B(S) + B(R)$
- So if one operand of the join fits in main memory, block nested loop is optimal
- Note that we can improve this result if R and/or S is clustered on disk


```
• Assumption: index on S.A
```

```
foreach block B of R {
  foreach tuple t in B \{suppose t.A = a;
    use the index to find all t2 in S with t2.A = a;
    write the join of t with each t2 to output;
  }
}
```


- $c = \text{cost of index access (roughly 2 or 3 for B-tree)}$
- \bullet μ = average number of tuples found
- \bullet $\mu \approx \frac{T(S)}{V(S, A)}$
- \bullet IO \approx B(R) + (c + μ)T(R)
- If A is primary key in S, $\mu = 1$
- This method might become interesting if the tuple size of R is large with respect to the block size of R

- The pseude code is given below
- An elaborate example will follow
- Note that any table R can be sorted in $IO = 4B(R)$

```
sort R on attribute A (if necessary);
sort S on attribute A (if necessary);
repeat {
  read the leading blocks from R and S
    containing the smallest common A-values;
  join the tuples in these blocks;
}
until R is finished or S is finished
```
Initial situation

After sorting on join attribute A

S A C a 33 a 88 b 51 b 14 b 11 c 97 c 46 c 72 ...

Copy leading blocks of both tables to buffer space

Sort-merge join: example

- Prepare partial join results in buffer space
- Partial join results are added tot Result table on disk

AddToResult

Copy new leading blocks of both tables to buffer space

S $A \mid C$ $b \mid 51$ $b \mid 14$ $b \mid 11$ c | 97 c 46 c 72

Sort-merge join: example

- Prepare partial join results in buffer space (blue)
- Partial join results are added tot Result table on disk

AddToResult

- Note that the buffer space generally consists of a lot of megabytes or even gigabytes
- Due to the small example size, it is suggested we handle only one join value in each iteration, but in reality, several join values will be dealt with
- We do not count for the cost of the join in main memory
- In extreme cases, the amount of data dealing with one single join value may exceed the buffer space
- In that case, techniques inspired by two-phase external sorting can be applied
- Cost of sorting: $4(B(R) + B(S))$
- Two way merge scan: $B(R) + B(S)$
- Total cost: $5(B(R) + B(S))$
- Note that this join method can be integrated with the merge sort of both operands; in that case $IO = 3(B(R) + B(S))$
- Two phase merge sort algorithms are applicable as long as $B(R) + B(S) \le M^2$
- M^2 is quite a lot

Hash join

- We will prepare hash buckets for both tables R and S
- Choose an appropriate size of M (number of buckets) for the hash buckets, based on table statistics
- Choose a hash function for the domain of A with codomain $0.0 M - 1$
- Each bucket has a buffer window to collect hashed tuples
- Scan through R and send each tuple to the appropriate bucket
- \bullet Scan through S and send each tuple to the appropriate bucket
- After scanning R and S, load each corresponding couple of R and S buckets into main memory and determine the join results for the tuples in these buckets
- Hash join works only for equi join

- Join $R[A, B]$ with $S[A, C]$
- hash function: $h(A) = A$ div 10¹

Not a very sophisticated hash function, but illustrative

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$$

• Create buckets for $h(A) = 0, 1, 2, ...$

_D

S2

• Read buckets for $h(A) = 0$ into buffer space

• Calculate joined tuples in buffer space

• Write joined tuples to the result table (buffered)

Result

• Read buckets for $h(A) = 1$ into buffer space

• Calculate joined tuples in buffer space

S2

 $\mathbf{C}\cap$

 $12 \mid m$

 $R1 \bowtie S1$

A	B	0
12	а	
12	a	m
12	b	
12	а	m

• Add joined tuples to the result table

Result

А	В	С
7	d	ı
12	a	
12	a	m
12	b	
12	b	m

• And repeat this for all buckets

Result

A	В	С
7	d	i
12	a	J
12	a	m
12	b	J
12	b	m
29	Ċ	h

Hash join: analysis

- Note that the total size of the two hashed tables is roughly $B(R) + B(S)$
- The cost of scanning $R: IO = B(R)$
- The cost of filling the hash buckets for R: IO \approx B(R)
- The cost of scanning S: $IO = B(S)$
- The cost of filling the hash buckets for S: $IO \approx B(S)$
- Scanning all hash buckets to calculate resulting tuples: $IO \approx B(R) + B(S)$
- We do not count for the cost of the join in main memory
- We ignore writing the result
- \bullet Overall cost: $IO \approx 3(B(R) + B(S))$

Epilog: OLTP vs OLAP

- Note that we often distinguish bnetween two kinds of applications for database management systems: OLTP and $OIAP$
- OLTP stands for online transaction processing
- A transaction oriented DBMS (*production database*) typically supports processing high volumes of small updates (commerce, banking, reservation systems)
- **•** Transactional integrity is of utmost importance
- Schema design for production databases focuses heavily on prevention of data redundancy and consistency (normalization)
- The amount of indices is limited to prevent update overhead, but some are essential for performance

OLTP vs OLAP

- Note that we often distinguish two kinds of applications for database management systems: OLTP and OLAP
- OLAP stands for online analytical processing
- An analysis oriented DBMS (analytical database, data warehouse) typically supports dealing with large and complex queries
- Analytical databases generally are created by taking snapshots from production databases
- These snapshots are extensively preprocessed
- Analytical databases typically are fixed for some time and read only
- Therefore, analytical databases generally do not support transaction processing
- An analysis oriented DBMS (analytical database, data warehouse) typically supports dealing with large and complex queries
- Support by indices is abundant
- Given the read only behaviour, data redundancy can be applied where necessary (materialized views)
- Analytical databases often comprise historical data
- Main memory database technology is an interesting candidate for analytical databases

OLTP and OLAP: example

- A large, countrywide grocery store deals with millions of transactions a day
- An OLTP system supports all checkouts and payments
- In most cases, transactions are connected to a known client
- An OLAP system provides overviews of all sales regarding to a certain period
- Market analysts may identify trends with respect to specific products, product groups, time periods, price development, and so on ...

Hans Philippi **[Query processing](#page-0-0) 1999** 49 / 50

OLTP and OLAP: example

- Market analysts may find opportunities for client directed offerings
- OLAP supports *market basket analysis*: product X is often bought in combination with product Y
- Market basket analysis has been one of the earliest challenges of data mining
- Find groups of articles that are often bought together

